

# Make Some Noise

## Unleashing the Power of Convolutional Neural Networks for Profiled Side-channel Analysis

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# Outline

- 1 Motivation
- 2 Side-channel Analysis
- 3 Deep Learning
- 4 Adding Noise
- 5 Results
- 6 Conclusions

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## What and Why

- Investigate the limits of CNNs' performance when considering side-channel analysis.
- Propose new CNN instance (and justify the choice for that instance).
- Investigate how additional, non-task-specific noise can significantly improve the performance of CNNs in side-channel analysis.
- Show how small changes in setup result in big differences in performance.

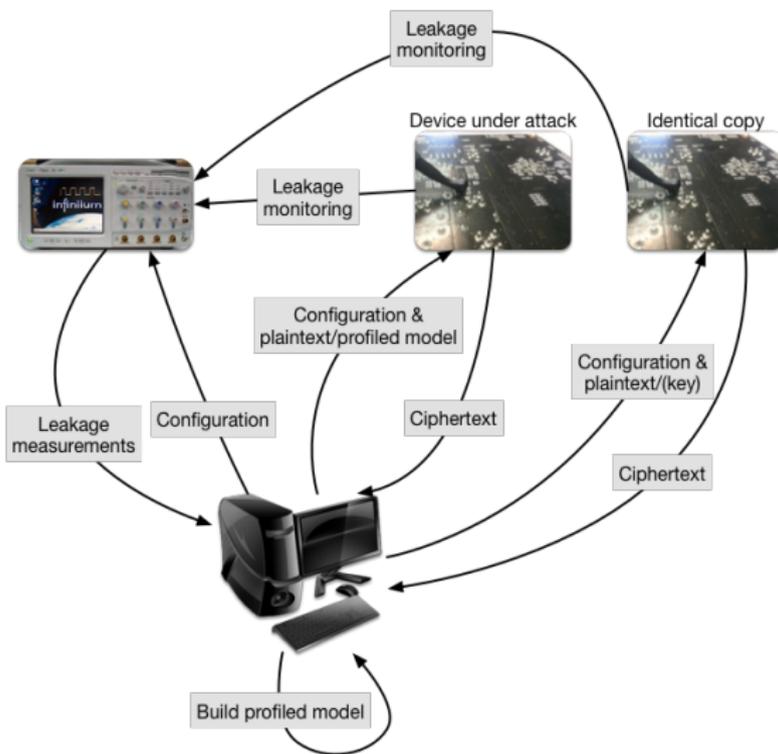
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## Profiled Attacks

- Side-channel attacks (SCAs) are passive, non-invasive implementation attacks.
- Profiled attacks have a prominent place as the most powerful among side channel attacks.
- Within profiling phase the adversary estimates leakage models for targeted intermediate computations, which are then exploited to extract secret information in the actual attack phase.

# Profiled Attacks



# Profiled Attacks

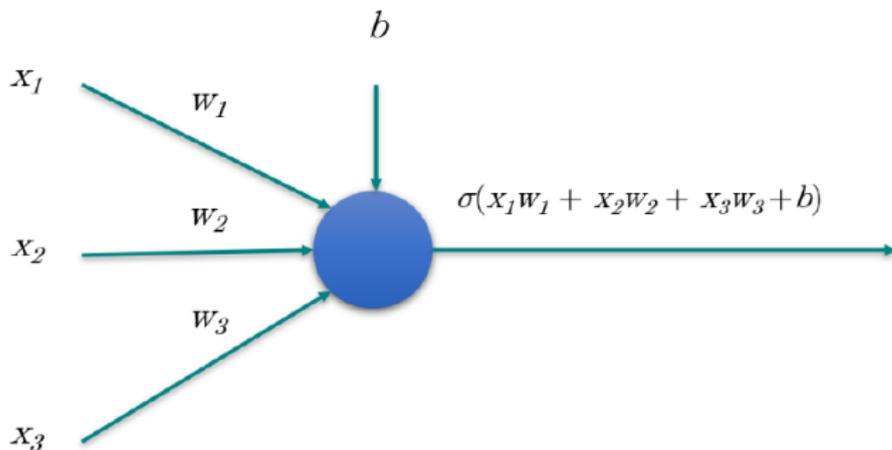
- Template Attack (TA) is the most powerful attack from the information theoretic point of view.
- Some machine learning (ML) techniques also belong to the profiled attacks.
- Deep learning has been shown to be able to reach top performance even if the device is protected with countermeasures.

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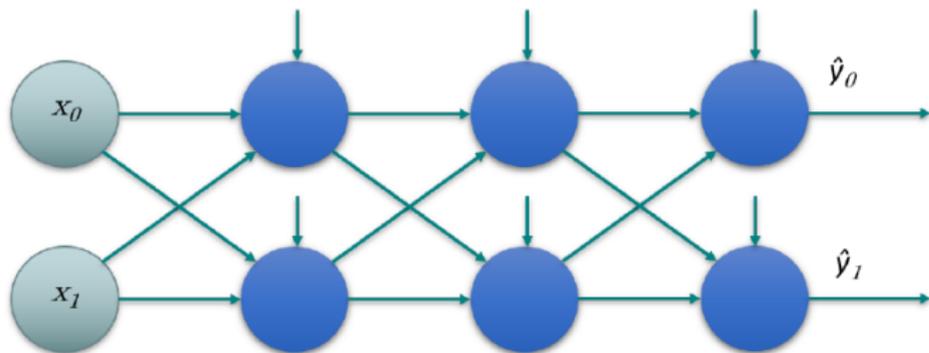
# Deep Learning

- Let us build a neural network.

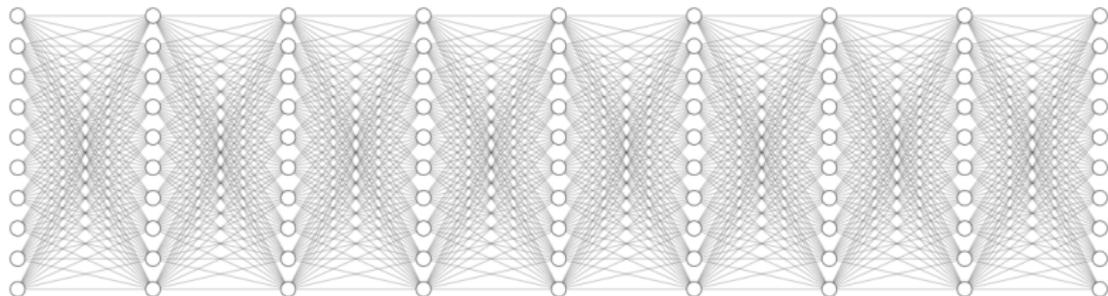


# Deep Learning

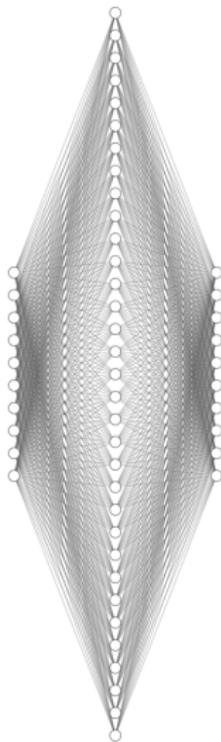
- Let us continue adding neurons.



# Multilayer Perceptron - “Many” Hidden Layers



# Multilayer Perceptron - One Hidden Layer



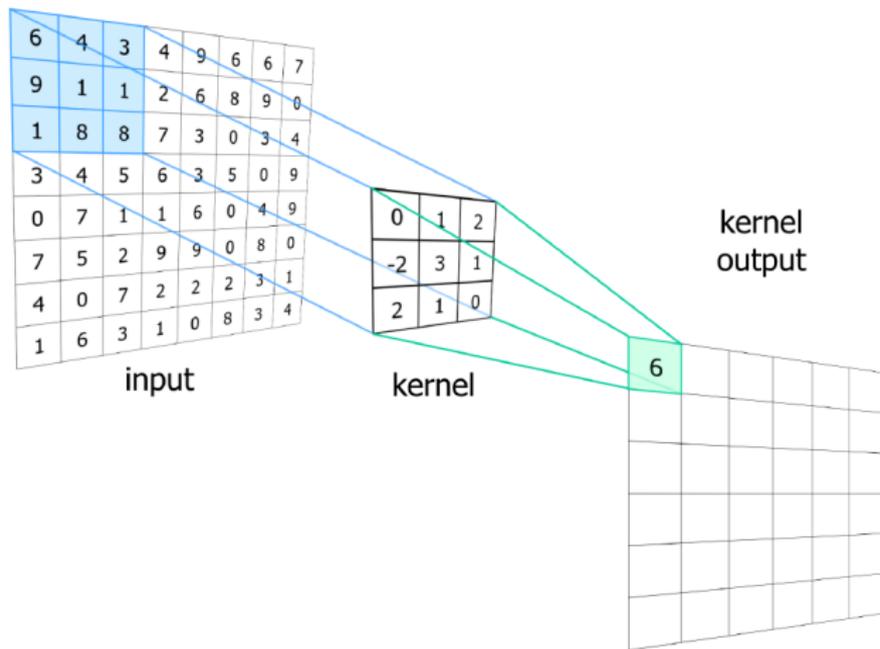
# Universal Approximation Theorem

- A feed-forward network with a single hidden layer containing a finite number of neurons can approximate continuous functions on compact subsets of  $\mathbb{R}^n$ .
- Given enough hidden units and enough data, multilayer perceptrons can approximate virtually any function to any desired accuracy.
- Valid results if and only if there is a sufficiently large number of training data in the series.

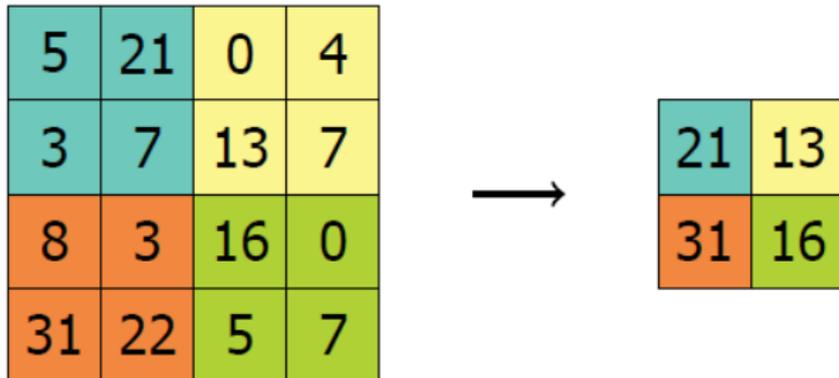
# Convolutional Neural Networks

- CNNs represent a type of neural networks which were first designed for 2-dimensional convolutions.
- They are primarily used for image classification but lately, they have proven to be powerful classifiers in other domains.
- From the operational perspective, CNNs are similar to ordinary neural networks: they consist of a number of layers where each layer is made up of neurons.
- CNNs use three main types of layers: convolutional layers, pooling layers, and fully-connected layers.

# Convolutional Neural Networks - Convolution Layer



# Convolutional Neural Networks - Pooling



## Design Principle - VGG Like CNN

- Small kernel size:  $3 \times 3$  for every layer.
- Max pooling with  $2 \times 2$  windows, with stride 2.
- Increasing number of filters per layer: doubled after every max pooling layer.
- Convolutional blocks are added until the spatial dimension is reduced to 1.
- After the fully connected layers is the output layer.
- The convolutional and fully connected layers use ReLu activations, the output layer uses Softmax to normalize the predictions.

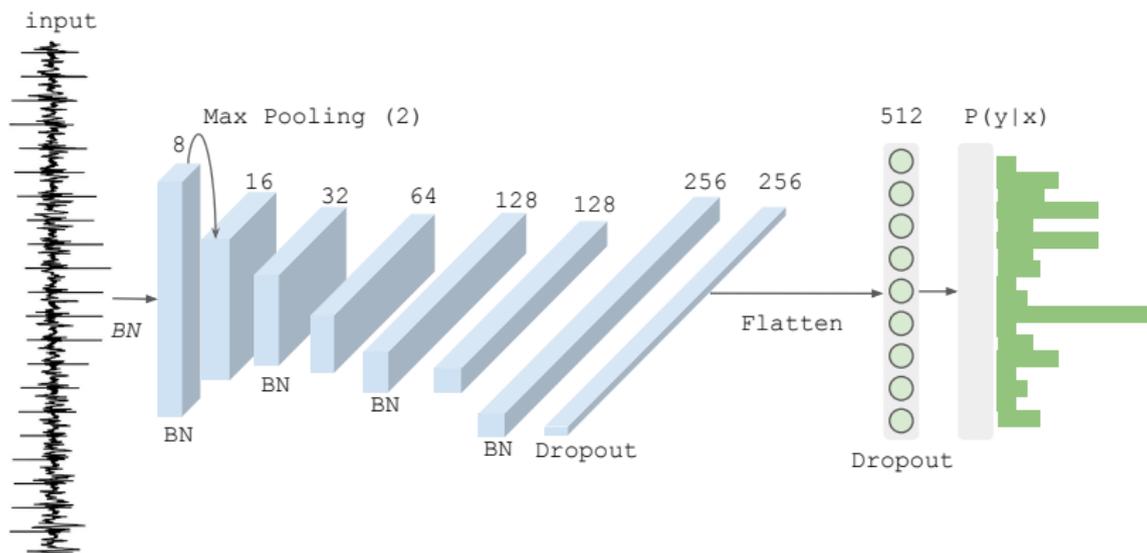
## Design Principle - VGG Like CNN

$$\text{net} = \text{fc}_{\theta, \text{softmax}} \circ \prod_{p=1}^P \text{fc}_{\theta^p, \text{ReLU}} \circ \prod_{q=1}^Q (\text{pool}_{\text{Max}} \circ \prod_{r=1}^{R_q} \text{conv}_{\phi^r, \text{ReLU}}), \quad (1)$$

$$\text{conv}_{\phi, \sigma}(X) = \sigma(\phi * X), \quad (2)$$

$$\text{fc}_{\theta, \sigma}(x) = \sigma(\theta^T x). \quad (3)$$

# Convolutional Neural Networks - Final



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## Why Adding Noise

- To reduce the overfitting of the model, we introduce noise to the training phase.
- Since in our case, the input normalization is also learned during the training process via the BN layer, we added the noise tensor after the first BN.

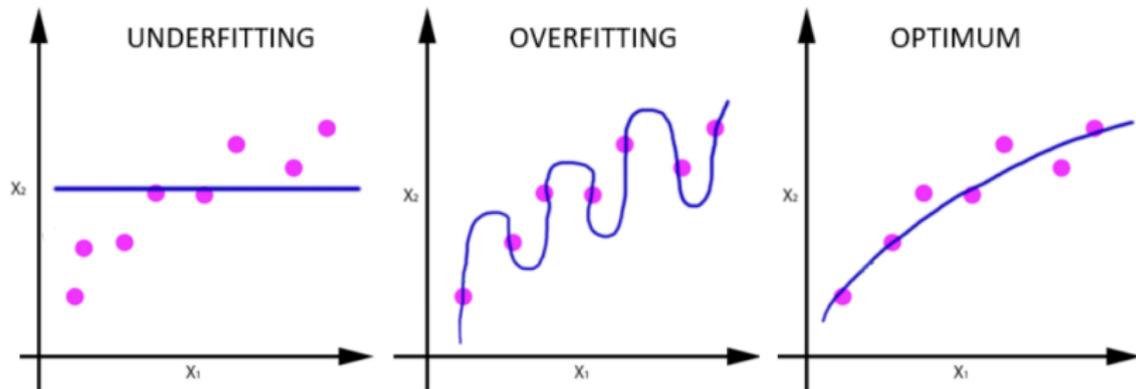
$$X^* = BN_0(X) + \Psi, \quad \Psi \sim \mathcal{N}(0, \alpha). \quad (4)$$

- The noise tensor follows the normal distribution.

# Data Augmentation

- Is this data augmentation?
- Data augmentation typically applies domain knowledge to deform the original signal into more “plausible” way and uses both the original and transformed measurements in the training phase.
- Our technique is a regularization technique and can be seen as 1) a noisy training and 2) data augmentation.
- We are closer to the noisy training as we neither: 1) add transformed measurements and 2) use domain-specific knowledge.

# Underfitting and Overfitting



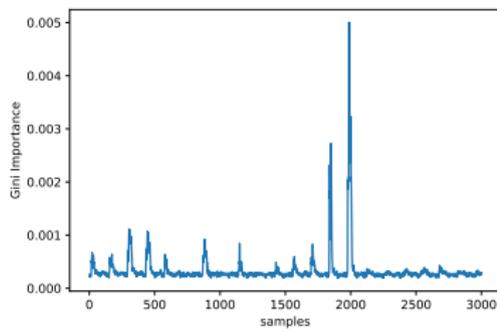
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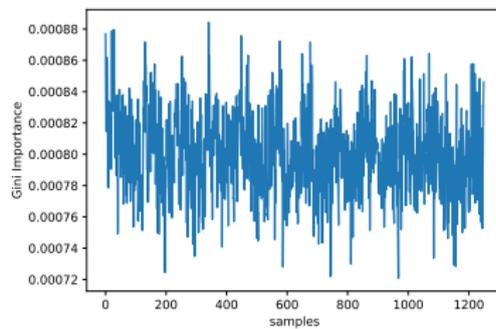
# Results

- We consider only the intermediate value model (256 classes).
- We experiment with CNNs, template attack, and pooled template attack.
- 4 publicly available datasets.

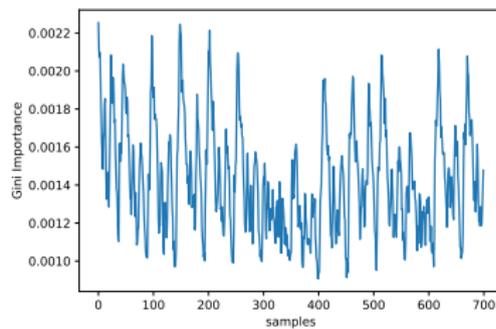
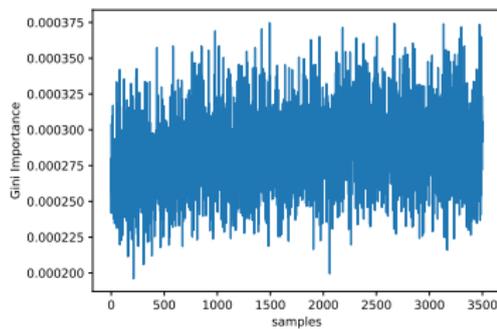
# Datasets



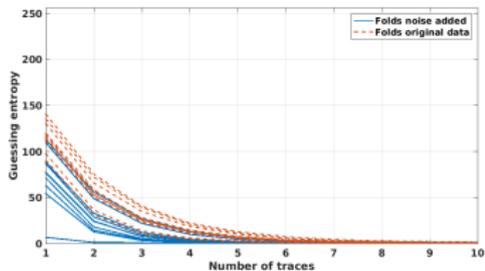
(a) DPAcontest v4 dataset.



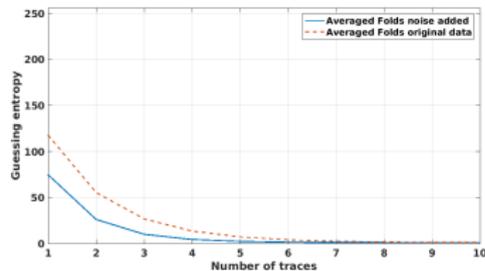
(b) AES\_HD dataset.



# Results DPAv4

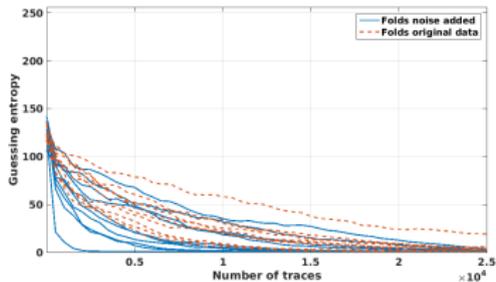


(a) RD network per fold.

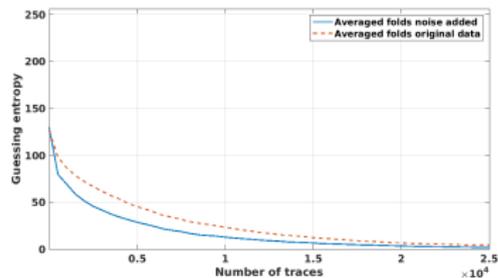


(b) RD network averaged.

# Results AES\_HD

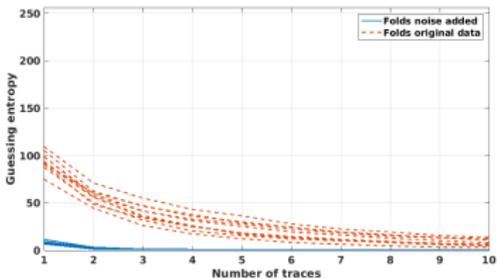


(a) ASCAD network per fold.

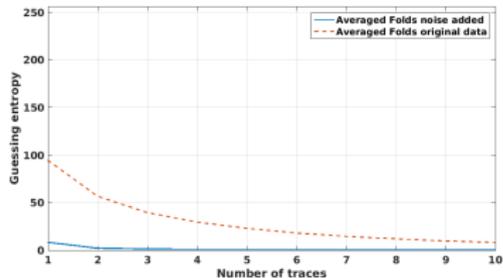


(b) ASCAD network averaged.

# Results AES\_RD

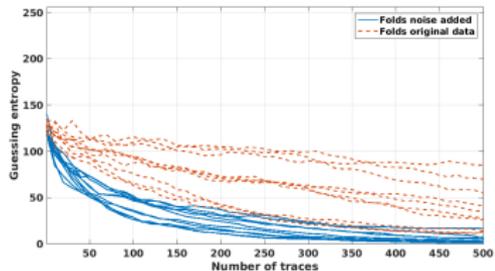


(a) RD network per fold.

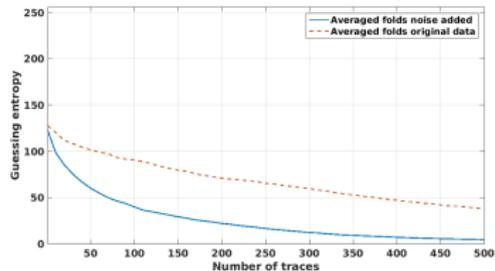


(b) RD network averaged.

# Results ASCAD



(a) ASCAD network per fold.

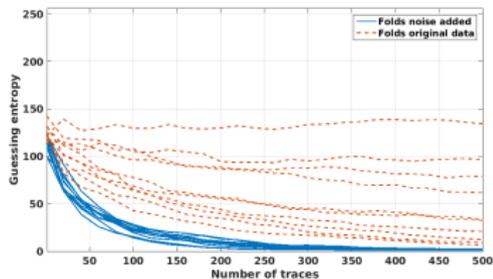


(b) ASCAD network averaged.

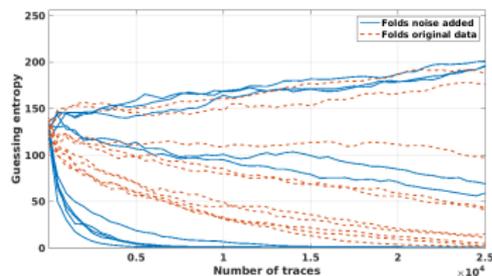
## What Else Do We Demonstrate

- We show noise addition to be quite stable over different levels of noise, number of epochs, and profiling set sizes.
- Our results indicate that it is not possible to have a single best CNN architecture even if considering “only” SCA.
- Attacking a dataset without countermeasure could be more difficult than attacking one that has countermeasures.
- What is really a new CNN architecture and what is simply a new instance in accordance to the input data?
- The less traces we have in the profiling phase, the more noise we need.

# Beware of the Choice of the Profiling Set



(a) ASCAD network per fold.



(b) RD network per fold.

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# Conclusions

- VGG-like CNNs seem to work very good for SCA.
- There are other domains that use machine learning/deep learning and we can learn a lot from them.
- Here, by using such good practices, we are able to reach top performance in SCA.
- We propose to add noise addition as a standard technique in the SCA evaluation for deep learning techniques.

## Questions?

Thanks for your attention! Q?